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(12) United States Patent Kishigami et al.

(54) WIRELESS COMMUNICATION DEVICE AND

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WIRELESS COMMUNICATION METHOD

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This patent is subject to a terminal dis-

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(30) Foreign Application Priority Data

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(Continued)

(52) U.S. Cl.

 (10) Patent No.: US 9,106,911 B2

(45) **Date of Patent:**

*Aug. 11, 2015

(58) Field of Classification Search

CPC H04N 21/2662; H04N 21/6582; H04N 21/44209; H04N 19/00054; H04N 19/00193;

H04N 19/00236

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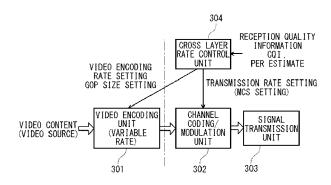
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(57) ABSTRACT

When controlling transmission channel parameters and video encoding parameters so as to be linked to each other in video transmission, the video quality on the receiving side is further improved. As a parameter control unit that controls video encoding parameters regarding video encoding in a video encoding unit and transmission channel parameters regarding error correction coding and modulation in a channel coding/modulation unit so as to be linked to each other, a cross layer rate control unit is provided. The cross layer rate control unit performs variable control of the GOP size according to propagation changes by reducing the GOP size when the predicted value of the PHY transmission rate is larger than a determined reference value and increasing the GOP size when the predicted value of the PHY transmission rate is equal to or less than the determined reference value.

8 Claims, 21 Drawing Sheets



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	H04N 11/04	(2006.01)
	H04N 19/114	(2014.01)
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	H04N 19/149	(2014.01)
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FIG. 1

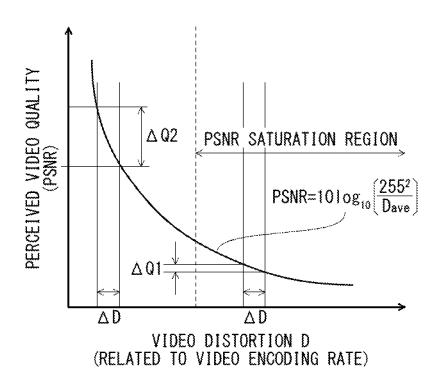


FIG. 2

GOP SIZE	AMOUNT OF VIDEO ENCODING DATA	VIDEO RECEPTION QUALITY (VARIATION FOLLOWABILITY)	
SMALL LARGE	INCREASE DECREASE	HIGH LOW	

FIG. 3

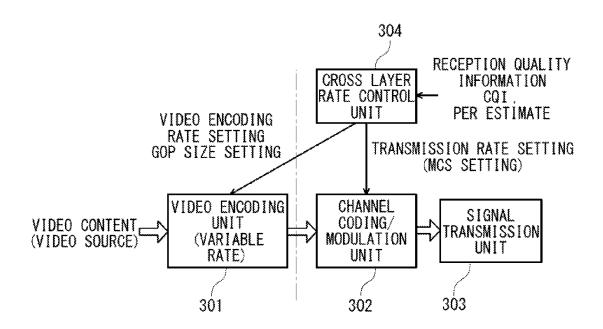


FIG. 4

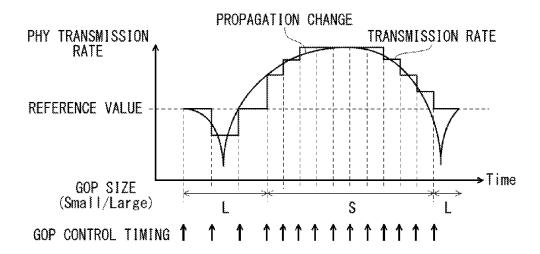


FIG. 5

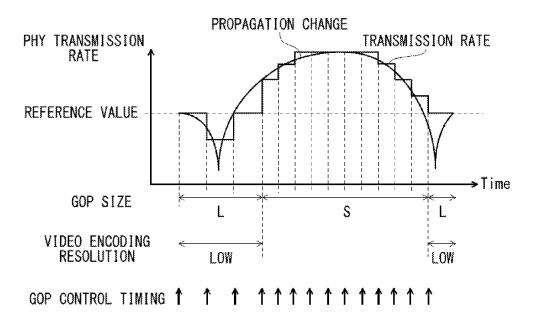


FIG. 6

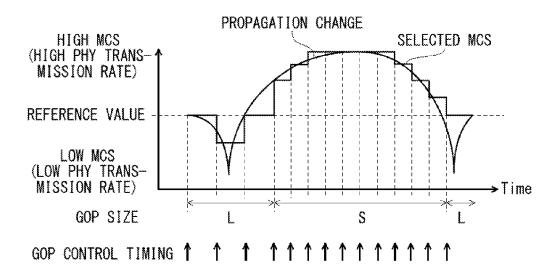
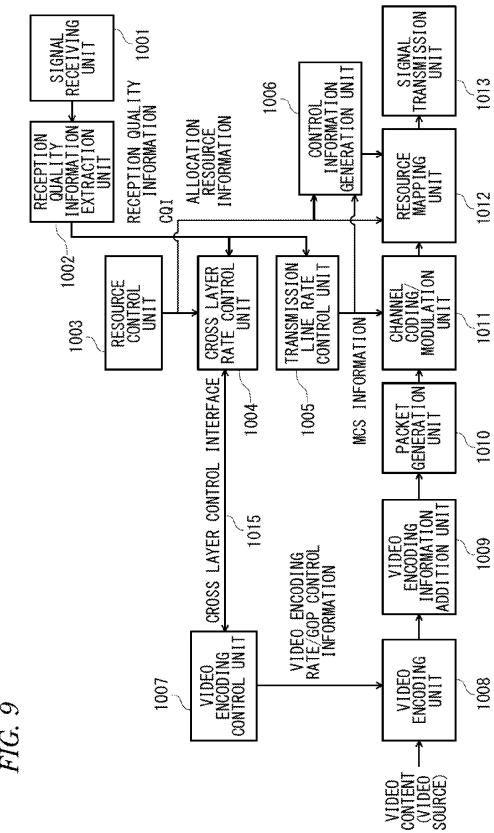


FIG. 7

	MCS	GOP SIZE	
	64QAM, R=5/6	GOP SMALL	
REGION		<u>*</u>	REFERENCE RATE (1)
	64QAM, R=1/2	GOP LARGE	103,2 (3)
	16QAM, R=3/4	GOP SMALL	
REGION	\		REFERENCE RATE (2)
	16QAM, R=1/2	GOP LARGE	1777
	QPSK, R=3/4	GOP SMALL	
REGION	•		REFERENCE RATE (3)
	QPSK, R=1/2	GOP LARGE	

FIG. 8

			_
	TRANSMIT RATE	GOP SIZE	
HIGH VIDEO ENCODING	10Mbps	GOP SMALL	
RATE REGION < ₹-	-		REFERENCE RATE (1)
(ex. HD TRANSMISSION)	1Mbps	GOP LARGE	(8)(22 ())
LOW VIDEO ENCODING	1.2Mbps	GOP SMALL	
RATE REGION < ⟨-	*		REFERENCE RATE (2)
(ex. SD TRANSMISSION)	100kbps	GOP LARGE	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,



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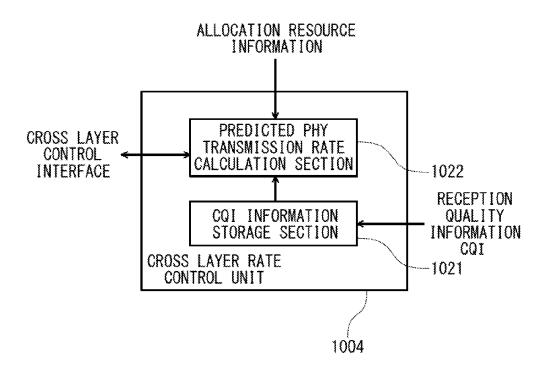
THE NUMBER OF IMAGES INCLUDED IN ONE GOP (IN CASE OF K=9) ೧೧ # # ಯ ۵. α d05 က

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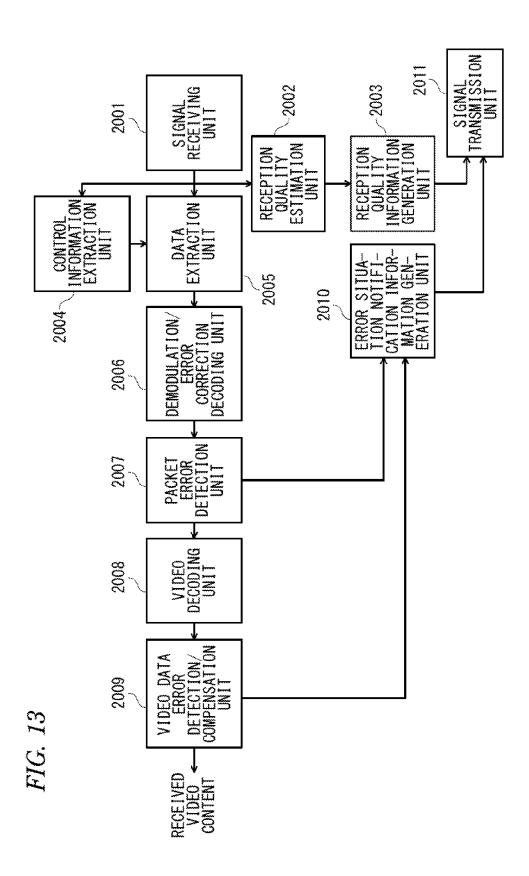
Aug. 11, 2015

FIG. 11



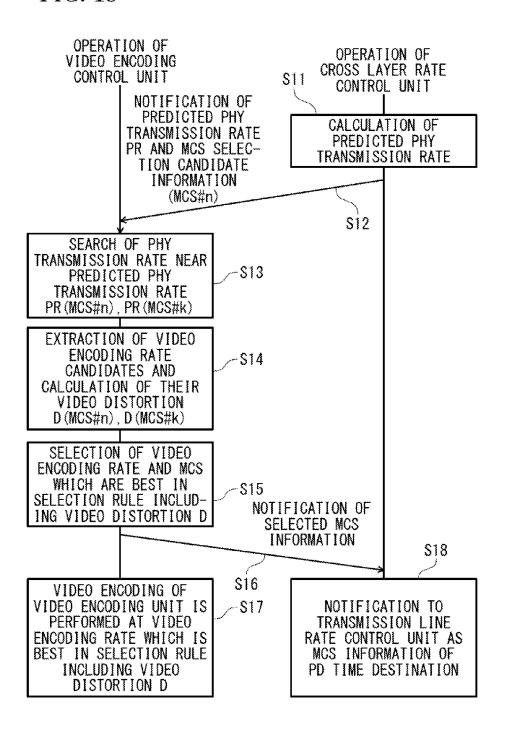
*

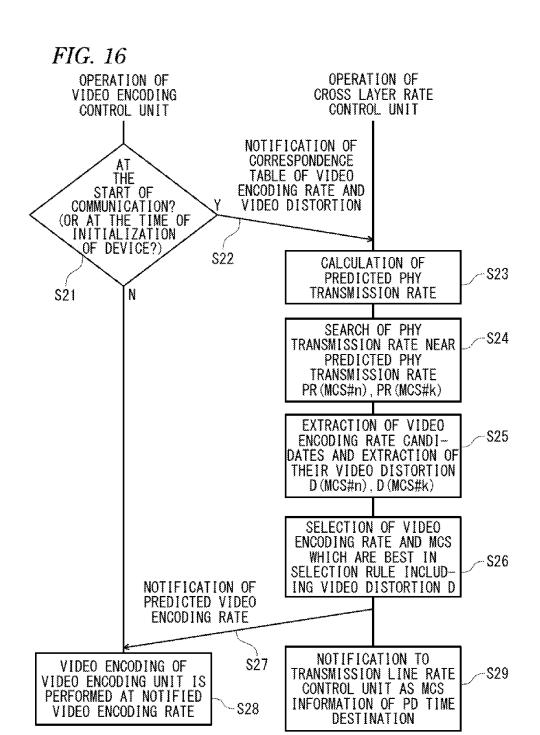
* * × GOP2 GOP3 GOP2 60P GOP2 GOP 1 G0P1

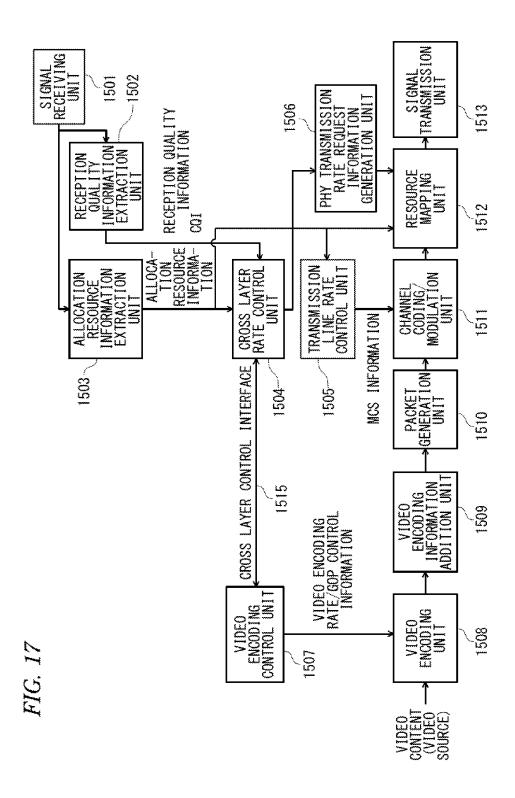


SIGNAL TRANSMISSION UNIT 1001 CONTROL INFORMATION GENERATION UNIT 1013 RECEPTION QUALITY INFORMATION RESOURCE MAPPING UNIT 1012 1002 CROSS LAYER RATE CONTROL UNIT TRANSMISSION LINE RATE CONTROL UNIT CHANNEL CODING/ MODULATION UNIT RESOURCE CONTROL UNIT 1011 MCS INFORMATION CROSS LAYER CONTROL INTERFACE 1104 010 1015 1009 VIDEO ENCODING CONTROL UNIT VIDEO ENCODING UNIT 1008 1107

FIG. 15







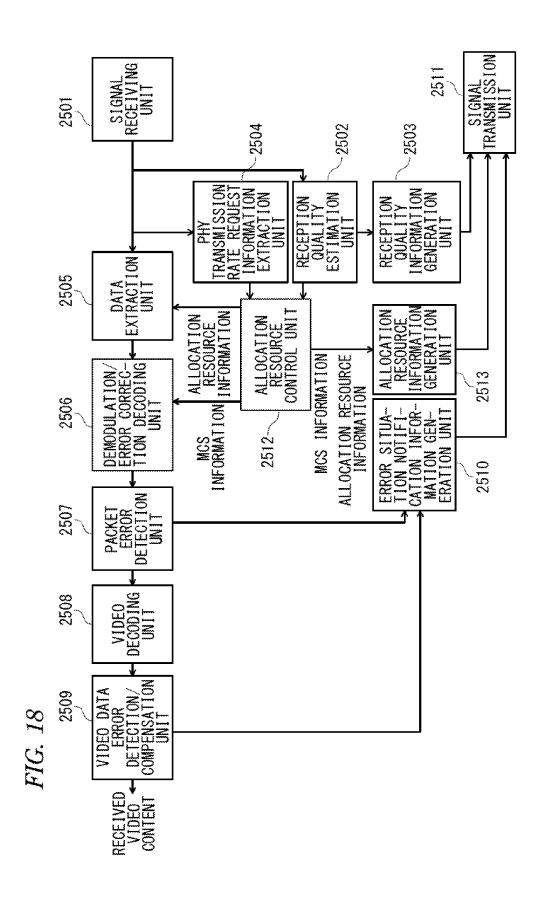


FIG. 19

	Web pages	Signalling	Audio Video	
Application (networking)	HTTP	RTSP	RTP	
Transport (networking)	TC	P	UDP	
Network	IP			
Data Link	Wimax, LTE. Wi-Fi, HDLC, Broadcast			
Physical [Copper, Fiber, Wireless			

FIG. 20

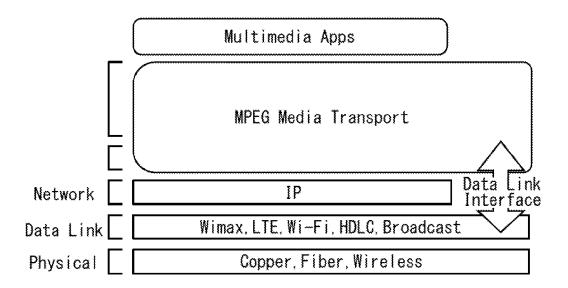
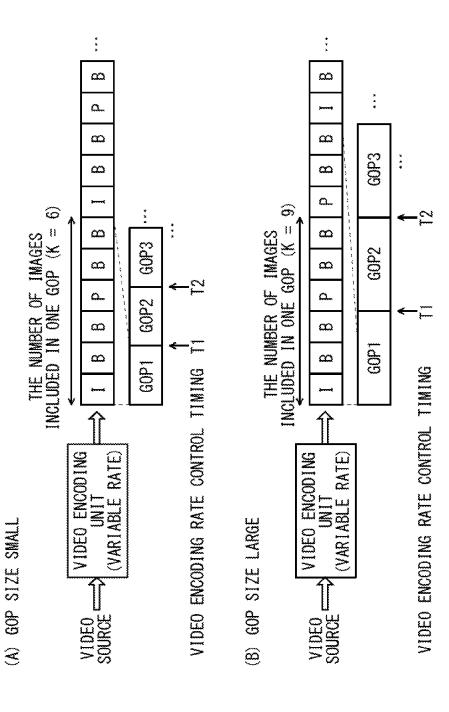


FIG. 2.1



WIRELESS COMMUNICATION DEVICE AND WIRELESS COMMUNICATION METHOD

TECHNICAL FIELD

The present invention relates to a communication device which performs video transmission and in particular, to a wireless communication device and a wireless communication method for performing video transmission using wireless transmission.

BACKGROUND ART

In the IEEE 802.16m (next generation WiMAX (Worldwide Interoperability for Microwave Access)), which is one of the standards of next generation wireless communication technology, or the MPEG (Moving Picture Experts Group), which is one of video data compression methods, cross layer optimization has been considered as new technology for 20 achieving high-efficiency and high-quality video transmission (refer to NPL 1). The cross layer optimization is a method of improving the overall performance by mutual notification of information between different layers and sharing the information between different layers so that protocols of 25 respective layers cooperate with each other. As the cross layer optimization in video transmission, a video encoding process in a layer (video encoding layer) in which encoding of the video content (including a moving image and a still image) is performed, such as an application layer, is linked to an error 30 correction coding (channel coding) process, which is performed to correct errors occurring at the time of wireless transmission (or cable transmission) of the video content in a physical layer (or a data link layer), for optimization of video transmission efficiency and the transmitted video quality.

FIG. 19 is a view showing a layer structure at the time of transmission of the multimedia content in the related art. In the related art, according to the OSI reference model which defines a hierarchical structure of a network, data is a data link layer, a network layer, a transport layer, and an application layer so that the process at the time of transmission is performed.

The cross layer optimization described above mainly includes the following two approaches (refer to NPL 2). In 45 addition, although a case where wireless transmission is applied as a transmission channel in the physical layer is described below, the transmission means is not limited to this, and similar application may also be made in cable transmission.

(1) Exchange of quality information and parameter information is performed between a layer in which video encoding is performed and a layer in which channel coding is performed. The following two methods may be considered as the method for information exchange between the application 55 layer and the physical layer (wireless layer). The first method is a method of introducing a direct interface between layers over a plurality of layers. The second method is a method of performing information exchange between cross-layer through the network layer (IP layer) in the middle with the 60 addition of header information that can be recognized. FIG. 20 is a view showing a layer structure at the time of transmission of the multimedia content under investigation in the MPEG. The example shown in FIG. 20 corresponds to the first method described above. In this example, an MPEG media transport layer is provided between a multimedia application and a data link layer, and information exchange is

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performed between the MPEG media transport layer and the data link layer and a physical layer.

(2) A quality evaluation measure (including the quality information of video encoding and the quality information of a transmission section) specific to video transmission is introduced, the transmission rate of a transmission section (wireless transmission section) of a physical layer and the video encoding rate are determined, and an operation to link these is performed. The quality evaluation measure specific to video transmission is disclosed in NPL 2. Here, video distortion D(R) when the transmission rate R of a physical layer and the video encoding rate are variable (under the conditions in which the used wireless resources are fixed) is included in the quality evaluation measure. The video distortion D(R) is related to the video encoding rate. The video distortion D(R) is small when the video encoding rate is high, and the video distortion D(R) is large when the video encoding rate is low. The quality evaluation measure $MCS_{SELECTED}$ including the video distortion D(R) is expressed by the following Expression (1).

[Expression 1]

50

$$MCS_{SELECTED} = \underset{MCS}{\operatorname{argmin}} D(R) * (1 - PER) + D_{max} * PER$$
 (1)

On the basis of this quality evaluation measure, the transmission rate and the video encoding rate of the transmission section of the physical layer are selected. In this manner, not only is the efficiency of video transmission increased, but also the effect of maintaining the video quality satisfactorily is obtained.

CITATION LIST

Patent Literature

[NPL 1] MPEG Workshop data, ISO/IEC JTC1/ exchanged between layers corresponding to a physical layer, 40 SC291WG11, MPEG09/1N11225, "Draft Modern Media Transport (MMT) Context and Objectives", January 2010, Kyoto, Japan

> [NPL 2] IEEE 802.16 WG letter, C80216-10/0007, Intel Corporation, January 2010

> [NPL 3] Shiba Okubo et al., "H.264/AVC textbook, revised third edition", impress R&D

SUMMARY OF INVENTION

Technical Problem

In H.264, MPEG2/MPEG4, and the like which are standardized for video encoding, a video encoding process is performed in units of GOP (Group of Pictures) as disclosed in NPL 3. An I picture subjected to coding within frames, a P picture subjected to predictive coding between forward frames, a B picture subjected to predictive coding between bidirectional frames, and header information of these pictures are included in one GOP, and these frames are encoded so as to be associated with each other. Accordingly, when the video encoding rate is variable, timing of a minimum unit of video encoding rate control is a GOP unit. In addition, in each video-encoded frame, the B picture has a highest compression rate, and the compression rate is reduced in the order of P picture and I picture.

FIG. 21 is a view showing an example of encoded video data when the GOP size is different. Hereinafter, the GOP size

will be defined and used as the number K of pictures included in the GOP. In FIG. 21, (A) shows an example when the GOP size is small (K=6), and (B) shows an example when the GOP size is large (K=9).

(A) When the GOP Size is Small

The ratio of the number of I pictures in a GOP is large. Accordingly, when other video encoding parameters are the same, the amount of encoded video data increases (compression rate decreases). In this case, depending on the video content, a probability of excessive video quality, such as a video with a small difference between frames, is increased. On the other hand, since the interval of video encoding rate control timing is short, followability when a band change (transmission rate change and propagation change) in a wireless transmission section occurs is increased.

(B) When the GOP Size is Large

The ratio of the number of I pictures in a GOP is small. Accordingly, when other video encoding parameters are the same, the amount of encoded video data decreases (compression rate increases). In this case, depending on the video content, a probability of degradation of the video quality, such as a video with a large difference between frames, is increased. On the other hand, since the interval of video encoding rate control timing is long, followability when a band change (transmission rate change and propagation 25 change) in a wireless transmission section occurs is reduced.

As described above, the GOP size may affect the video quality. Therefore, depending on the video content, the video quality on the receiving side may be degraded if the GOP size is not appropriately set. In the above-described method disclosed in NPL 2, when controlling the transmission channel parameters (PHY transmission rate and the like) and the video encoding parameters (video encoding rate and the like), the GOP size is not taken into consideration. For this reason, depending on the state of the transmission channel or the like, 35 a desired video quality may not be secured as the video quality on the receiving side.

An object of the invention is to make it possible to further improve the video quality on the receiving side, when controlling the transmission channel parameters and the video encoding parameters so as to be linked to each other in video transmission.

Solution to Problem

According to one aspect of the present invention, there is provided a wireless communication device comprising:

- a video encoding unit configured to perform video encoding on video data;
- a channel coding and modulation unit configured to perform error correction coding and modulation on the encoded video data;
- a signal transmission unit configured to transmit channel coded video data after the error correction coding and modulation; and
- a control unit configured to perform variable control of a GOP (Group of Pictures) size in the video encoding on the basis of a size of a transmission channel parameter corresponding to a predicted value of a transmission rate on a transmission channel through which the channel coded video 60 data is transmitted

In the wireless communication device according to this invention, the GOP size is controlled so as to become smaller than a determined size when the transmission channel parameter is larger than a determined reference value.

In the wireless communication device according to this invention, the GOP size is controlled so as to become larger 4

than the determined size when the transmission channel parameter is equal to or less than the determined reference

In the wireless communication device according to this invention, when the GOP size is controlled so as to become larger than the determined size, the control unit reduces a video encoding rate or a frame rate in the video encoding.

In the wireless communication device according to this invention, when changing the GOP size, the control unit changes the GOP size according to a changing rate of the GOP size.

In the wireless communication device according to this invention, the transmission channel parameter is at least one of a PHY transmission rate in a physical layer and an MCS (Modulation and Coding Scheme) indicating an encoding rate and a modulation method in the error correction coding and modulation.

In the wireless communication device according to this invention, the control unit divides the PHY transmission rate or the MCS into a plurality of regions and performs variable control of the GOP size according to a reference value set for each region.

In the wireless communication device according to this invention, the determined reference value is a reference value of a transmission channel parameter determined on the basis of a value indicating a boundary between a saturation region, which is a region where a change in an evaluation value of perceived video quality is small, and the region where a change in the evaluation value of the perceived video quality is large with respect to a change in video distortion changing in association with a change in a video encoding rate.

According to another aspect of the present invention, there is provided a wireless communication method of a wireless communication device which performs transmission of video data, the method comprising:

performing video encoding on the video data;

performing error correction coding and modulation on encoded video data after the video encoding;

transmitting channel coded video data after the error correction coding and modulation; and

performing variable control of a GOP (Group of Pictures) size in the video encoding on the basis of a size of a transmission channel parameter corresponding to a predicted value of a transmission rate on a transmission channel through which the channel coded video data is transmitted.

In the above-described configuration, when the transmission channel parameter is higher than a predetermined reference value, it becomes easy to follow propagation changes by reducing the GOP size. As a result, it is possible to improve the video quality. When the transmission channel parameter is equal to or less than the predetermined reference value, an increase in the amount of encoded video data when the GOP size is reduced can be absorbed by increasing the GOP size. In this case, it is possible to apply encoding to increase the degree of redundancy further in error correction coding of transmission data. Accordingly, since the transmission channel error rate can be reduced, it is possible to improve the video quality. Therefore, when controlling the transmission channel parameters and the video encoding parameters so as to be linked to each other in video transmission, it is possible to improve the video quality on the receiving side under propagation changes.

Advantageous Effects of Invention

According to the present invention, when controlling the transmission channel parameters and the video encoding

parameters so as to be linked to each other in video transmission, the video quality on the receiving side can be further improved.

BRIEF DESCRIPTION OF DRAWINGS

FIG. 1 is a graph showing the relationship between the PSNR (Perceived Signal to Noise Ratio), which indicates a measure of the perceived video quality, and video distortion D at the time of video encoding.

FIG. 2 is a view showing the relationship of the amount of encoded video data and the video reception quality (variation followability) with respect to the GOP size.

FIG. 3 is a block diagram showing the configuration of a main part of a wireless communication device related to an 15 embodiment of the present invention.

FIG. 4 is a view showing a control operation of cross layer optimization in a first embodiment.

FIG. 5 is a view showing a control operation of cross layer optimization in a second embodiment.

FIG. 6 is a view showing a control operation of cross layer optimization in a third embodiment.

FIG. 7 is a view showing a control operation of cross layer optimization in a fourth embodiment.

FIG. **8** is a view showing a control operation of cross layer 25 optimization in a fifth embodiment.

FIG. 9 is a block diagram showing the configuration of a wireless transmission device related to a first example.

FIG. **10** is an explanatory view of the operation showing outputs of a video encoding unit and a video encoding information addition unit.

FIG. 11 is a block diagram showing an example of the configuration of a cross layer rate control unit.

FIG. 12 is an explanatory view of the operation showing the timing of an output of a video encoding unit and an output of a channel coding/modulation unit.

FIG. 13 is a block diagram showing the configuration of a wireless receiving device related to a first example.

FIG. **14** is a block diagram showing the configuration of a wireless transmission device related to a first modification of 40 the first example.

FIG. 15 is a flow chart showing the procedure of determining the video encoding rate and the PHY transmission rate in consideration of the video distortion related to the first modification of the first example.

FIG. **16** is a flow chart showing the procedure of determining the video encoding rate and the PHY transmission rate in consideration of the video distortion related to a second modification of the first example.

FIG. 17 is a block diagram showing the configuration of a 50 wireless transmission device related to a fifth example.

FIG. **18** is a block diagram showing the configuration of a wireless receiving device related to the fifth example.

FIG. 19 is a view showing a layer structure at the time of transmission of the multimedia content in the related art.

FIG. 20 is a view showing a layer structure at the time of transmission of the multimedia content under investigation in the MPEG.

FIG. 21 is a view showing an example of encoded video data when the GOP size is different.

DESCRIPTION OF EMBODIMENTS

In the present embodiment, as an example of a wireless communication device and a wireless communication 65 method related to the present invention, an example of the configuration of a device that can be applied to the commu6

nication standard, such as IEEE 802.16m, is shown. Here, the configuration and operation for performing cross layer optimization, which is to optimize the video quality by linking channel coding and modulation in a physical layer or a data link layer and video encoding in an application layer or the like, will be described in detail.

The present invention notes that differences in video quality can be distinguished more easily by the senses in regions with smaller video distortion (region with a higher video encoding rate). It is known that the perceived video quality is relatively highly correlated with a PSNR (Perceived Signal to Noise Ratio or Peak Signal to Noise Ratio). FIG. 1 is a graph showing the relationship between the perceived video quality and video distortion D at the time of video encoding when the PSNR shown in the following Expression (2) is used, for example.

[Expression 2]

$$PSNR = 10\log_{10}\left(\frac{255^2}{D_{avs}}\right) \tag{2}$$

As also can be seen from FIG. 1, the PSNR changes according to the logarithm of the reciprocal of the video distortion D. The PSNR decreases as the video distortion D increases, and the amount of change decreases gradually and the PSNR is saturated. It can be seen that a variation $\Delta Q1$ of the PSNR with respect to a variation ΔD of video distortion in a region where the video distortion D is relatively large (PSNR saturation region) is smaller than a variation $\Delta Q2$ of the PSNR with respect to the variation ΔD of video distortion in a region where the video distortion D is relatively small (region not included in the PSNR saturation region). This means that a video quality difference can be distinguished by the senses more easily in a region with the smaller video distortion D (region with a higher video encoding rate). Here, the video distortion D changes in connection with a change in the video encoding rate. The image distortion D has a qualitative characteristic in which it becomes small by increasing the video encoding rate high for the same video content.

FIG. 2 is a view showing the relationship between the amount of encoded video data with respect to the GOP size and the image receiving quality (variation followability). As the GOP size decreases in a state where other video encoding parameters are fixed, the amount of encoded video data increases (that is, the compression rate becomes low) or the interval of video encoding rate control timing becomes short. Accordingly, followability to band changes in the transmission channel (transmission rate change and propagation change) can be increased. Accordingly, since it is possible to provide the video reception quality according to the situation of the transmission channel, it is possible to improve the video reception quality. On the contrary, as the GOP size increases, the amount of encoded video data decreases (that is, the compression rate becomes high) or the interval of video encoding rate control timing becomes long. Accordingly, fol-60 lowability to band changes in the transmission channel (transmission rate change and propagation change) is degraded. This leads to a decrease in the video reception quality.

In the present embodiment, parameters at the time of video transmission are controlled on the basis of the characteristics of the perceived video quality PSNR and the characteristics of the GOP size. In this case, one of the following three controls is performed.

(1) Followability to propagation changes is increased by reducing the GOP size more for a region with a higher video encoding rate. In this manner, it is possible to reduce the variation ΔD regarded as a difference from the video distortion achieved when following a propagation change ideally. 5 As a result, it is possible to improve the perceived video quality.

(2) The amount of encoded video data is reduced by increasing the GOP size more for a region with a lower video encoding rate (region where it is difficult to detect a perceived video quality difference), thereby increasing the compression rate. In this case, since the video encoding rate is reduced, there is room for the transmission rate at which transmission in a physical layer is possible. Accordingly, it is possible to perform an operation for cooperation between layers so that encoding to increase the degree of redundancy further is applied in error correction coding in a physical layer or a data link layer. By performing such a cooperation operation, it is possible to reduce the transmission channel error rate in a wireless transmission section in a region with a low video encoding rate without increasing the resource allocation size. As a result, it is possible to improve the video quality.

(3) (1) and (2) are combined. That is, the GOP size is reduced more for a region with a higher video encoding rate, while the GOP size is increased more for a region with a lower 25 video encoding rate. In this case, since the video encoding rate is reduced, an operation for cooperation between layers is performed so that encoding to increase the degree of redundancy further is applied in error correction coding in a physical layer or a data link layer. In this manner, it is possible to 30 improve the video quality in both a region with a higher video encoding rate and a region with a lower video encoding.

For an increase in the amount of encoded video data according to a reduction in the compression rate caused by reducing the GOP size in the above (3), the increase in the 35 amount of encoded video data can be absorbed by increasing the GOP size in the region with a lower video encoding rate (region where it is difficult to detect a perceived video quality difference). Accordingly, a further effect is obtained in which the video reception quality under propagation changes is 40 improved while suppressing an increase in the amount of encoded video data. In particular, a further effect can be obtained in which, when a plurality of wireless communication devices share the limited resources of the wireless transmission section in performing video transmission, the video 45 reception quality of each wireless communication device can be improved.

FIG. 3 is a block diagram showing the configuration of a main part of a wireless communication device related to the embodiment of the present invention. The wireless commu- 50 nication device of the present embodiment includes a video encoding unit 301, a channel coding/modulation unit 302, a signal transmission unit 303, and a cross layer rate control unit 304. The cross layer rate control unit 304 sets transmission channel parameters according to the transmission rate of 55 the transmission channel and video encoding parameters, such as a video encoding rate (quantization size) and the GOP size, on the basis of CQI (Channel Quality Information) and reception quality information, such as a PER (Packet Error Rate) estimation value. In addition, setting and control of 60 these parameters may be performed separately or performed together partially according to an instruction of the cross layer rate control unit 304 by providing a control unit for each of the setting and the control. As the setting of the transmission channel parameters, setting of the PHY transmission rate 65 in a physical layer, MCS (Modulation and Coding Scheme) setting which determines an encoding rate and a modulation

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scheme according to the transmission channel situation (propagation quality), or the like is performed. Here, the cross layer rate control unit 304 realizes a function of a parameter control unit.

The video encoding unit 301 performs video encoding of video data (video source) which has the video content including a moving image and a still image as a source. In this case, the video encoding unit 301 can perform video encoding at the variable rate, and performs the encoding process according to the video encoding rate and the GOP size set on the basis of the control of the cross layer rate control unit 304. For the encoded video data, the channel coding/modulation unit 302 performs an error correction coding process of the designated encoding rate and a modulation process based on the designated modulation scheme according to the PHY transmission rate, the MCS, and the like set on the basis of the control of the cross layer rate control unit 304. The signal transmission unit 303 transmits the symbolic data after modulation to the wireless transmission channel as a wireless signal

Examples of a wireless communication device and a wireless communication method of performing a parameter control operation regarding the video encoding rate, the GOP size, the PHY transmission rate, the MCS, and the like at the time of video transmission are shown in the following embodiments. In each embodiment, an example of the operation when a band change (propagation change) in a wireless transmission section occurs with time due to the influence of fading or the like and accordingly the transmission rate (PHY transmission rate) in a wireless transmission section changes will be described.

First Embodiment

FIG. 4 is a view showing a control operation of cross layer optimization in a first embodiment. In the first embodiment, when performing parameter control for cross layer optimization, a parameter update interval is variable, and parameters are set such that the PHY transmission rate and the GOP size are associated with each other. That is, variable control of the GOP size is performed according to the PHY transmission rate (linked to band changes (propagation changes) in a physical layer).

In this case, when the PHY transmission rate is higher than a determined reference value, the GOP size is changed to Small (S). In this case, when the PHY transmission rate is equal to or lower than the determined reference value, the GOP size is changed to Large (L). Here, regarding the reference value, a reference transmission rate is set from the reference value (for example, a PSNR saturation region boundary value) of the video encoding rate. Alternatively, it is also possible to use relative values, such as an average PHY transmission rate and an initial transmission rate.

If the transmission rate at which transmission in a physical layer is possible is increased due to propagation changes, the video encoding rate can be increased and accordingly the video distortion D is reduced. When the transmission rate is further increased to exceed a determined reference value, that is, when the video distortion D becomes equal to or lower than the PSNR saturation region and accordingly a region is generated where a video quality difference can be easily distinguished by the senses, the video quality can be improved by reducing the GOP size, which is a video encoding unit, to increase follovvability to propagation changes. That is, when the PHY transmission rate is higher than the reference value, propagation change followability in a high video encoding rate region is increased by changing the GOP size to Small. As

a result, since the variation ΔD of video distortion in FIG. 1 is further reduced, it is possible to improve the perceived video quality. In addition, when the PHY transmission rate is equal to or lower than the reference value, the compression rate in a low video encoding rate region where it is difficult to detect a 5 perceived video quality difference is increased by changing the GOP size to Large. As a result, an increase in the amount of encoded video data is absorbed. In this case, since there is room for the transmission rate, at which transmission in a physical layer is possible, due to a reduction in the amount of encoded video data, it is possible to apply encoding (encoding of a low encoding rate) to increase the degree of redundancy further in error correction coding of transmission data. Therefore, it is possible to reduce the transmission channel error 15 rate in a low video encoding rate region without increasing the resource allocation size in a wireless transmission section. As a result, it is possible to improve the video quality. By the above control operation, when controlling the transmission channel parameters and the video encoding parameters so as 20 to be linked to each other in video transmission, the video quality on the receiving side can be improved. In addition, it is possible to improve the video reception quality under propagation changes while suppressing an increase in the amount of encoded video data.

Second Embodiment

FIG. 5 is a view showing a control operation of cross layer optimization in a second embodiment. In the second embodiment, when performing parameter control for cross layer optimization, the video encoding resolution is adjusted in addition to the control of the first embodiment. When controlling the GOP size according to the PHY transmission rate, the GOP size is changed to Large while reducing the video 35 encoding resolution if the PHY transmission rate is equal to or lower than a reference value. As the video encoding resolution, the video encoding rate (spatial resolution) or the frame rate (time resolution) is reduced. In addition, it is also possible to increase the number of I pictures when reducing the frame 40 64QAM, and the like). rate (in the case of thinning out frames).

When the PHY transmission rate is equal to or lower than the reference value, the video encoding rate (frame rate) and the PHY transmission rate are matched to each other by ensuring the minimum video quality in a situation where the transmission channel conditions (propagation quality) are poor. In this manner, it is possible to suppress noticeable degradation of the video reception quality at the time of low transmission rate. In addition, in error correction coding in a 50 physical layer or a data link layer, it is possible to apply encoding (encoding at the low encoding rate) for increasing the degree of redundancy further. As a result, since it is possible to suppress the degradation of the video quality, it is possible to improve the video reception quality.

Third Embodiment

FIG. 6 is a view showing a control operation of cross layer optimization in a third embodiment. In the third embodiment, 60 when performing parameter control for cross layer optimization, a parameter update interval is variable, the MCS is used as a transmission channel parameter, and parameters are set such that an MCS setting and the GOP size are associated with each other. That is, variable control of the GOP size is performed according to the MCS setting situation (linked to band changes (propagation changes) in a physical layer).

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Here, a case where the allocation resource of the wireless communication device is fixed is assumed.

In this case, when the MCS setting is a higher MCS (equivalent to the high PHY transmission rate) than the determined reference value, the GOP size is changed to Small (S). On the other hand, when the MCS setting is a lower MCS (equivalent to the low PHY transmission rate) than the determined reference value, the GOP size is changed to Large (L). Here, regarding the reference value, a reference MCS is set from the reference value (for example, a PSNR saturation region boundary value) of the video encoding rate. Alternatively, it is also possible to use an MCS setting value based on average PHY transmission rate, an initial MCS setting value, and the like.

When the MCS setting is higher than the reference value, propagation change followability in a high video encoding rate region is increased by changing the GOP size to Small. As a result, since the variation ΔD of video distortion in FIG. 1 is further reduced, it is possible to improve the perceived video quality. In addition, when the MCS setting is equal to or lower than the reference value, the compression rate in a low video encoding rate region where it is difficult to detect a perceived video quality difference is increased by changing the GOP size to Large. As a result, an increase in the amount of 25 encoded video data is absorbed. In this case, since there is room for the transmission rate, at which transmission in a physical layer is possible, due to a reduction in the amount of encoded video data, it is possible to apply encoding (encoding of a low encoding rate) to increase the degree of redundancy further in error correction coding of transmission data. Therefore, it is possible to reduce the transmission channel error rate in a low video encoding rate region without increasing the resource allocation size in a wireless transmission section. As a result, it is possible to improve the video quality. By the above control operation, in addition to the effect of the first embodiment, the error rate at the time of video transmission can be further improved by changing the GOP size to Small in a high-modulation multi-value region with relatively low resistance to errors by propagation changes (16QAM,

Fourth Embodiment

FIG. 7 is a view showing a control operation of cross layer reducing the video encoding rate or the frame rate, thereby 45 optimization in a fourth embodiment. In the fourth embodiment, when performing parameter control for cross layer optimization, a parameter update interval is variable, the MCS is used as a transmission channel parameter, an MCS set is divided into a plurality of regions, and variable control of the GOP size is performed according to the reference rate in each region.

FIG. 7 shows an example in which an MCS set is divided into regions (1) 64QAM, (2) 16QAM, and (3) QPSK for the same modulation level of MCS. Each region is a set of MCS 55 with the same modulation level and different encoding rates. Here, in each region, the GOP size is changed to Small when the encoding rate is higher than a reference rate, and the GOP size is changed to Large when the encoding rate is equal to or lower than the reference rate. In addition, the reference rates (1), (2), and (3) of the respective regions in this case are encoding rates, and different values may be set for the regions or the same value may be set for the regions. Since resistance to errors decreases as the encoding rate increases, the GOP size is changed to Small to improve the error rate at the time of video transmission. In addition, although a region is divided according to the modulation level in the example described above, it is also possible to divide a region accord-

ing to the encoding rate, set the modulation level as a reference rate, and perform control to change the GOP size according to the size of the modulation level with respect to the reference rate. In addition, for the changed GOP size, sizes of Large/Small may be set as different values in respective regions. By the above control operation, the error rate of video transmission with respect to propagation changes can be reduced by selecting the GOP size on the basis of error resistance. As a result, it is possible to improve the video reception quality.

Fifth Embodiment

FIG. **8** is a view showing a control operation of cross layer optimization in a fifth embodiment. In the fifth embodiment, when performing parameter control for cross layer optimization, a parameter update interval is variable, the PHY transmission rate is used as a transmission channel parameter, the PHY transmission rate is divided into a plurality of regions, and variable control of the GOP size is performed according to the reference rate in each region. In addition, a plurality of divided regions may have transmission rate overlap portions.

FIG. 8 shows an example in which the PHY transmission rate is divided into a high video encoding rate region (10 25 Mbps to 1 Mbps) where, for example, HD (High Definition, high-resolution image quality) transmission and a low video encoding rate region (1.2 Mbps to 100 kbps) where, for example, SD (Standard definition, standard-resolution image quality) transmission. Here, in each region, the GOP size is changed to Small when the encoding rate is higher than a reference rate, and the GOP size is changed to Large when the encoding rate is equal to or lower than the reference rate. Accordingly, in each of the high video encoding rate region and the low video encoding rate region, the GOP size is changed on the basis of the perceived video quality in the region. In addition, for the changed GOP size, sizes of Large/ Small may be set as different values in respective regions. By the above control operation, the video reception quality in $_{40}$ each transmission rate region can be improved by selecting the GOP size on the basis of a perceived video quality reference for each of the plurality of transmission rate regions.

Modifications of the above embodiment are shown below.

First Modification

When changing the GOP size, a rate of change in the GOP size may be given instead of switching between the value of the large GOP and the value of the small GOP. Accordingly, it 50 is possible to meet a case where the video encoding unit performs video encoding by changing the GOP size.

Second Modification

At the timing before video encoding of a GOP unit starts, the selection of the PHY transmission rate (or MCS selection) is performed. In this case, in consideration of a transmission delay ΔD until the encoded video data is actually transmitted through the transmission channel from the input of the video $_{0}$ encoding unit and a feedback delay ΔFB until the control information from the transmission channel is transmitted to the video encoding unit, a PHY transmission rate at the time which is ahead by time ($\Delta D+\Delta FB$) is predicted on the basis of a fading frequency of the transmission channel or the like. For example, between video encoding rate control timings (GOP size control timings), linear prediction based on a plurality of

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measurement results is performed. Therefore, it is possible to select more appropriate transmission channel parameters.

Third Modification

Information regarding the current parameter setting values (MCS, video encoding rate, and the like) and only the near parameters is exchanged between layers to estimate the video distortion. That is, the size in a direction in which the video encoding rate increases or decreases is increased to estimate the video distortion. In this manner, it is possible to estimate the video distortion precisely while reducing the amount of processing and the amount of information related to processing, and it is possible to set parameters, such as the GOP size, appropriately on the basis of the video distortion estimation result.

Hereinafter, as wireless communication devices corresponding to the embodiments described above, examples of the more specific configuration and processing of a wireless transmission device and a wireless receiving device are shown. Here, the wireless transmission device corresponds to a component with a signal transmission function in the wireless communication device, and the wireless receiving device corresponds to a component with a signal receiving function in the wireless communication device.

First Example

A first example corresponds to the first embodiment described above.

The first example is an example applied to downlink video transmission in a state where the wireless transmission device is a base station of the wireless communication system and the wireless receiving device is a terminal of the wireless communication system. In this case, the wireless transmission device (base station) assigns wireless resources in the host device, and transmits video data to the wireless receiving device (terminal).

Configuration and Operation of the Wireless Transmission Device

FIG. 9 is a block diagram showing the configuration of the wireless transmission device related to the first example. The wireless transmission device is configured to include a signal receiving unit 1001, a reception quality information extraction unit 1002, a resource control unit 1003, a cross layer rate control unit 1004, a transmission channel rate control unit 1005, a control information generation unit 1006, a video encoding control unit 1007, a video encoding unit 1008, a video encoding information addition unit 1009, a packet generation unit 1010, a channel coding/modulation unit 1011, a resource mapping unit 1012, and a signal transmission unit 1013. Here, the cross layer rate control unit 1004 and the video encoding control unit 1007 realize a function of the parameter control unit.

The resource control unit 1003 determines the allocation of the resource at a time and a frequency, which is used for video transmission, among the available wireless resources (frequency carrier band) and outputs the allocation resource information. As the allocation resource information, resource position information, resource size information, resource arrangement information (distributed allocation or localized allocation), and the like are included. In addition, the allocation resource information includes MCS information, which is information regarding the encoding rate R and modulation

scheme information (QPSK, 16QAM, 64QAM, and the like), in the channel coding/modulation unit **1011** when performing video transmission.

The signal receiving unit 1001 receives wireless signals transmitted from one or a plurality of wireless communication devices, which are partners that perform video transmission through wireless communication, through an antenna and performs frequency conversion of the received signals from the carrier frequency band to the baseband frequency band. The reception quality information extraction unit 1002 to extracts CQI, as reception quality information of the wireless transmission channel transmitted from the wireless communication partner, on the basis of the signals received by the signal receiving unit 1001.

The transmission channel rate control unit **1005** sets the 15 encoding rate R and the modulation scheme information (QPSK, 16QAM, 64QAM, and the like) used in the channel coding/modulation unit **1011**, as MCS information, on the basis of the reception quality information CQI acquired from the reception quality information extraction unit **1002**, and 20 outputs the MCS information to the channel coding/modulation unit **1011**.

The control information generation unit 1006 generates information including allocation resource information, such as transmission data destination information, resource position information, resource size information, resource arrangement information, and MCS information, and various kinds of information as control information based on a predetermined format.

The video encoding unit 1008 performs video encoding of 30 the video content (video source), which has video data including a moving image or a still image as a source, on the basis of the output of the video encoding control unit 1007. As video encoding, video encoding methods, such as H.264 and MPEG, are used. In H.264, MPEG2/MPEG4, and the like 35 which are standardized, the video encoding process is performed in units of GOP as disclosed in NPL 3. An I picture subjected to encoding in frames, a P picture subjected to predictive coding between forward frames, and a B picture subjected to predictive coding between bidirectional frames 40 are included in a GOP, and these frames are encoded so as to be associated with each other. Accordingly, timing of a minimum unit of video encoding rate control is a GOP unit. In addition, in each video-encoded frame, the B picture has the highest compression rate, and the compression rate is smaller 45 in the order of P picture and I picture. Hereinafter, the GOP size will be defined and used as the number K of pictures included in the GOP

The video encoding information addition unit 1009 adds an encoding parameter, which is used at the time of video encod- 50 ing in the video encoding unit 1008, to the GOP unit as video encoding information. FIG. 10 is an explanatory view of the operation showing outputs of a video encoding unit and a video encoding information addition unit. FIG. 10 shows an example in the case of GOP size K=9. The video encoding 55 unit 1008 outputs encoded video data, which is performed in units of GOP, as GOP#n (n=1, 23, ...). The video encoding information addition unit 1009 adds video encoding information to each header #n of the n-th GOP#n and outputs the result. The packet generation unit 1010 forms a packet based 60 on a predetermined format for the output of the video encoding information addition unit 1009 and outputs the result. In addition, a CRC (Cyclic Redundancy Check) bit for error detection is added to each packet.

The channel coding/modulation unit **1011** performs channel coding (transmission channel encoding) and modulation for the input packet on the basis of the MCS information

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(including the encoding rate and the modulation scheme) designated from the transmission channel rate control unit 1005. In this case, the channel coding/modulation unit 1011 generates coded bit data by performing an error correction coding process with the designated encoding rate R, and also generates symbol data by performing modulation on the basis of the designated modulation scheme (QPSK, 16QAM, 64QAM, and the like).

The resource mapping unit 1012 maps the control information on the resource determined in advance, and assigns the output of the channel coding/modulation unit 1011 to the wireless resource at the time and frequency on the basis of the allocation resource information designated from the resource control unit 1003. Here, when OFDMA (Orthogonal Frequency Division Multiple Access) is used as secondary modulation, the resource size is set with a resource unit, which includes a predetermined number of subcarriers and a predetermined number of OFDM symbols, as a minimum allocation unit. The signal transmission unit 1013 performs frequency conversion of the output of the resource mapping unit 1012 from the baseband frequency band to the carrier frequency band and outputs the result to the wireless transmission channel through an antenna so that the result is transmitted to the wireless communication device of the communication partner.

The cross layer rate control unit 1004 predicts the transmission rate (PHY transmission rate) of a wireless transmission section on the basis of the allocation resource information and the reception quality information CQI, and notifies the video encoding control unit 1007 of the result through the cross layer control interface (I/F) 1015.

FIG. 11 is a block diagram showing an example of the configuration of the cross layer rate control unit. The cross layer rate control unit 1004 is configured to include a CQI information storage section 1021 and a predicted PHY transmission rate calculation section 1022. The CQI information storage section 1021 stores the reception quality information CQI acquired from the reception quality information extraction unit 1002 in a storage memory with a circular buffer configuration. The predicted PHY transmission rate calculation section 1022 predicts a PHY transmission rate, and calculates a PHY transmission rate PR (predicted PHY transmission rate) of the prediction result. Here, the PHY transmission rate prediction process is performed as follows. In consideration of a processing time PD until the n-th video encoding unit GOP#n encoded and output by the video encoding unit 1008 is transmitted through the wireless transmission path, the CQI estimate of the PD time destination is calculated from the reception quality situation of a current and a previous time of the CQI information storage section 1021 which stores the reception quality information CQI. Then, an MCS (MCS#n) by which the target packet error rate (PER) is acquired is selected, and the transmission rate in a wireless transmission section is calculated using the allocation resource information.

FIG. 12 is an explanatory view of the operation showing the timing of an output of the video encoding unit and an output of the channel coding/modulation unit. FIG. 12 shows the output timing of each unit when the video content (video source) is input in units of a GOP. In addition, within the GOP, the order of data may be changed by interleaver or the like.

Here, focusing on the n-th GOP#n (n=1, 2, 3, ...), the time when video encoding on the video source included in the GOP#n is started in the video encoding unit 1008 is Tn, and the time when output of the encoded video data is started in the channel coding/modulation unit 1011 is (Tn+ Δ D). Here, Δ D is a transmission delay taken from the input of the video

encoding unit 1008 to the output of the channel coding/modulation unit 1011. In addition, in the control system of the video encoding unit 1008, a jitter (variation) Δ FB of the processing delay or transmission delay until the prediction result of the PHY transmission rate in the cross layer rate control unit 1004 is notified to the video encoding control unit 1007 through the cross layer control interface 1015 may be expected. In consideration of this time, the PHY transmission rate prediction in the cross layer rate control unit 1004 is performed by predicting the time PD ($=\Delta D + \Delta FB$) destination from the 10 present. In addition, the timing Sn at which the predicted value of the PHY transmission rate is notified to the video encoding control unit 1007 is notified from the video encoding control unit 1007 to the cross layer rate control unit 1004 through the cross layer control interface 1015. Here, the timing Sn is a time of ($Tn-\Delta FB$). On the basis of this timing notification, the cross layer rate control unit 1004 notifies the video encoding control unit 1007 of the predicted value of the PHY transmission rate at time Sn. The predicted value of the PHY transmission rate is calculated by applying linear pre- 20 diction based on a plurality of CQI information items obtained at timing intervals (Sn-1, Sn) notified to the video encoding control unit 1007.

In this manner, the video encoding control unit 1007 can acquire the predicted value of the PHY transmission rate for 25 video encoding control unit 1007, which is performed the GOP#n at the timing before video encoding of the target GOP#n starts. On the basis of the predicted value of the PHY transmission rate, the video encoding control unit 1007 can set parameters of video encoding, such as a GOP size change, a quantization size change, and a frame rate change, according to band changes in the wireless transmission channel (transmission rate change and propagation change).

In addition, although the example shown in the drawings has been described using the case where the GOP size is fixed, the above may similarly be applied to a case where the GOP 35 size is variable. In addition, the PD which is a prediction time of the PHY transmission rate may be set in advance as a fixed value, or it is possible to use a value obtained by measuring a processing delay using the test pattern. Alternatively, the PD may be notified as a parameter from the video encoding 40 control unit 1007 to the cross layer rate control unit 1004 through the cross layer control interface 1015.

The video encoding control unit 1007 determines parameters, such as the GOP size, the quantization size Q, and the video size when performing video encoding, on the basis of 45 the information of the predicted value of the PHY transmission rate from the cross layer rate control unit 1004 acquired through the cross layer control interface 1015. Then, the video encoding control unit 1007 notifies the video encoding unit 1008 of the determined parameter and performs variable 50 control of the video encoding rate for the video encoding unit **1008**. Here, as the quantization size Q, a quantization size Q which becomes the last video encoding rate comparable to or less than the predicted value of the PHY transmission rate is selected. On the other hand, the GOP size is changed as 55 follows.

The video encoding control unit 1007 compares the PHY transmission rate with a reference value according to changes in the predicted value of the PHY transmission rate due to propagation changes on the basis of the information regarding 60 the predicted value of the PHY transmission rate from the cross layer rate control unit 1004, and changes the GOP size according to the difference from the reference value. In this case, as shown in FIG. 4, the GOP size is changed to the smaller size (GOP size small: S) when the predicted value of 65 the PHY transmission rate is higher than the reference value, and the GOP size is changed to the larger size (GOP size: L)

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when the predicted value of the PHY transmission rate is equal to or lower than the reference value. Here, the reference value is assumed to be the video encoding rate which becomes a PSNR saturation region boundary shown in FIG. 1. Alternatively, the reference value may be assumed to be the PHY transmission rate set at the start of video transmission.

In addition, the GOP size may be given as a rate of change in the GOP size instead of switching between the large GOP and the small GOP. In this case, for the standard GOP size (or the GOP size at the start of video transmission), when the predicted value of the PHY transmission rate is larger than the reference value, a value obtained by multiplying the GOP size by the rate of change smaller than 1 and rounding off the result to an integral value is used as the GOP size Small (S). On the other hand, when the predicted value of the PHY transmission rate is equal to or less than the reference value, a value obtained by multiplying the GOP size by the rate of change larger than 1 and rounding off the result to an integral value is used as the GOP size Large (L). Such control based on the rate of change of the GOP size is suitable for a case of performing video encoding by changing the GOP size according to the video content.

As described above, the interval of parameter update to the through the cross layer control interface 1015 in the cross layer rate control unit 1004, can be changed on the basis of the video encoding timing of the GOP unit in the video encoding unit 1008, and the PHY transmission rate (transmission band width) and the GOP size can be controlled so as to be associated with each other. That is, the GOP size can be changed according to the size of the PHY transmission rate (propagation change).

When the transmission rate at which transmission using the wireless transmission channel is possible is increased due to propagation changes and exceeds a determined reference value, that is, when the video distortion D becomes equal to or lower than the PSNR saturation region and accordingly a region is generated where a video quality difference can easily be distinguished by the senses, the video quality can be improved by reducing the GOP size, which is a video encoding unit, to increase followability to propagation changes. That is, when the PHY transmission rate is higher than the reference value, propagation change followability in a high video encoding rate region is increased by changing the GOP size to Small. As a result, it is possible to improve the perceived video quality. In addition, when the PHY transmission rate is equal to or lower than the reference value, the compression rate in a low video encoding rate region where it is difficult to detect a perceived video quality difference is increased by changing the GOP size to Large. As a result, an increase in the amount of encoded video data can be absorbed. In this manner, it is possible to improve the video reception quality while suppressing an increase in the amount of encoded video data.

In addition, in the above example, on the basis of the information of the predicted value of the PHY transmission rate from the cross layer rate control unit 1004, variable control of the GOP size when performing video encoding is performed by the video encoding control unit 1007. However, the subject of control may be replaced. That is, the same effect may also be obtained in a configuration in which the cross layer rate control unit 1004 determines the GOP size on the basis of the reference value of the PHY transmission rate and the cross layer rate control unit 1004 sends a notification to the video encoding control unit 1007.

Configuration and Operation of the Wireless Receiving Device

FIG. 13 is a block diagram showing the configuration of the wireless receiving device related to the first example. The 5 wireless receiving device is configured to include a signal receiving unit 2001, a reception quality estimation unit 2002, a reception quality information generation unit 2003, a control information extraction unit 2004, a data extraction unit 2005, a demodulation/error correction decoding unit 2006, a 10 packet error detection unit 2007, a video decoding unit 2008, a video data error detection/compensation unit 2019, an error situation notification information generation unit 2010, and a signal transmission unit 2011.

The signal receiving unit 2001 receives a wireless signal transmitted from the wireless communication device, which is a partner that performs video transmission through wireless communication, through an antenna and performs frequency conversion of the received signal from the carrier frequency band to the baseband frequency band. On the basis of the signal received by the signal receiving unit 2001, the reception quality estimation unit 2002 estimates the reception quality of the wireless transmission channel between the partner device and the host device, for example, using a reception result of a reference signal. The reception quality information unit 2003 generates CQI as the reception quality information on the basis of the output of the reception quality estimation unit 2002.

When the signal received by the signal receiving unit 2001 has been subjected to secondary modulation, such as 30 OFDMA, the control information extraction unit 2004 performs the demodulation operation to extract the modulated symbolic data in which notification information is included, thereby extracting the control information. Here, the control information includes allocation resource information, such as 35 transmission data destination information, resource position information, resource size information, resource arrangement information, and MCS information.

When the signal received by the signal receiving unit 2001 has been subjected to secondary modulation, such as 40 OFDMA, the data extraction unit 2005 performs the demodulation operation to extract the modulated symbolic data destined for the host device on the basis of extracted control information. The demodulation/error correction decoding unit 2006 converts the extracted symbolic data into channel-coded (transmission-channel-coded) bit data by performing demodulation processing based on the designated modulation scheme (QPSK, 16QAM, 64QAM, and the like) on the extracted symbolic data. In addition, the demodulation/error correction decoding unit 2006 performs an error correction 50 decoding process on the channel-coded bit data.

The packet error detection unit 2007 detects whether or not the packet has been received successfully on the basis of the CRC bit for error detection added to each packet. Then, according to the error detection result, unique index information given to each packet and ACK (reception OK) are output as packet error information to the error situation notification information generation unit 2010 when the packet has been received correctly, and unique index information given to each packet and NACK (reception NG) are output as packet error information to the error situation notification information generation unit 2010 when the packet has not been received correctly.

The video decoding unit **2008** stores primarily the packet received successfully in a buffer, and starts a video decoding process when the data which makes up the smallest unit of video encoding is prepared. Here, when the video content is

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transmitted in real time, if the data which makes up the minimum unit of video encoding is not prepared in real time, processing for discarding the packet data acquired until then is performed. In the video decoding process, the video decoding unit 2008 decodes the video data according to the encoding parameter set on the transmission side on the basis of the video encoding information included in the packet, thereby reproducing the received video content.

The video data error detection/compensation unit 2009 detects a loss (video data error) of the video data based on a packet which has not been acquired in real time. In addition, when the loss of video data is detected, compensation for the video data is performed (Error Concealment). As compensation for video data, for example, video data on the same screen from previously is used again on the basis of the position on the screen (on the field) formed by the video data. As a result, degradation of the video quality can be suppressed. In addition, when the loss of video data is detected at a predetermined frequency or higher, the information is output to the error situation notification information generation unit 2010 as video data loss information.

The error situation notification information generation unit 2010 generates error situation notification information, in a format in which each error can be distinguished, from the packet error information in the packet error detection unit 2007 or the video data loss information (detection information of the number of block errors of a video encoding unit [for example, a thread unit]) in the video data error detection/compensation unit 2009. The signal transmission unit 2011 performs frequency conversion of the error situation notification information and the reception quality information CQI from the baseband frequency band to the carrier frequency band and outputs the result to the wireless transmission channel through an antenna so that the result is transmitted to the wireless communication device of the communication partner.

First Modification of the First Example

As a first modification of the first example, a first example in which a method of determining the video encoding rate and the PHY transmission rate has been changed is shown. In PHY transmission rate prediction processing, the cross layer rate control unit and the video encoding control unit may calculate the predicted PHY transmission rate and select the MCS using information of video distortion D caused by video encoding.

FIG. 14 is a block diagram showing the configuration of the wireless transmission device related to the first modification of the first example. In this first modification, operations of a cross layer rate control unit 1104, a transmission channel rate control unit 1105, and a video encoding control unit 1107 are different from those in the first example described above, and a video distortion calculation unit 1121 that calculates the video distortion D is further provided. The cross layer rate control unit 1104 outputs to the transmission channel rate control unit 1105 an MCS selection result when the information of the video distortion D caused by video encoding is taken into consideration. The video encoding control unit 1107 performs control of the video encoding process and transmission of the video distortion D information to the cross layer rate control unit 1104 using the video distortion calculated by the video distortion calculation unit 1121.

FIG. 15 is a flow chart showing the procedure of determining the video encoding rate and the PHY transmission rate in consideration of the video distortion related to the first modification of the first example. The cross layer rate control unit

1104 calculates the predicted PHY transmission rate PR in the same manner as the cross layer rate control unit 1004 in the first example shown in FIG. 11 (S11). Then, the cross layer rate control unit 1104 notifies the video encoding control unit 1007 of the calculated (predicted) PHY transmission 5 rate PR and MCS#n used at the time of calculation of the PHY transmission rate PR, as MCS selection candidate information, through the cross layer control interface 1015.

The video encoding control unit 1107 searches for a plurality of MCS#k (here, k=2 or more and approximately 4 or 10 less), which achieves a bit rate equal to the bit rate per modulation symbol (bits/symbol) obtained by the MCS#n or a bit rate in the periphery close to the bit rate per modulation symbol (including a case exceeding the bit rate per modulation symbol and a case less than the bit rate per modulation 15 symbol), with the notified MCS selection candidate information (MCS#n). Then, the PHY transmission rates PR(MCS#n) and PR(MCS#n) when these MCS#n and MCS#k are used are calculated (S13).

Then, the video encoding control unit 1107 selects a quan- 20 tization size Q, which becomes the last video encoding rate comparable to or less than the calculated PHY transmission rates PR(MCS#n) and PR(MCS#n), and extracts the selected quantization size as video encoding rate candidates. The video distortion calculation unit 1121 receives these video 25 encoding rate candidates, calculates the video distortion D(MCS#n) and D(MCS#k) at the time of each application, and outputs the result to the video encoding control unit 1107 (S14). The video encoding control unit 1107 selects a video encoding rate and an MCS which are the best (which mini- 30 mizes the video distortion D) according to the selection rule considering the video distortion D (S15).

Here, there are two methods of selecting the MCS which minimizes the video distortion D. (Method 1) From the calculation values of the video distortion D(MCS#n) and 35 D(MCS#k), the MCS which minimizes the video distortion D is selected from MCS#n and MCS#k. (Method 2) The calculation values of the video distortion D(MCS#n) and D(MCS#k) are multiplied by weighting coefficients (PER) in each transmission, and the MCS which becomes a minimum value among them is selected from MCS#n and MCS#k. Here, the weight coefficient when the PER is taken into consideration can be calculated by α(MCS#k)=PER (MCS#k)/Target_PER using PER(MCS#k) when MCS#k is 45 applied in the reception quality (SINR) which achieves the target PER (Target_PER) when the cross layer rate control unit 1104 selects MCS#n as an MCS selection candidate. In this case, $\alpha(MCS#n)=PER (MCS#n)/Target_PER=1$.

Then, the video encoding control unit 1107 notifies the 50 cross layer rate control unit 1104 of the selection MCS information indicating the selected MCS through the cross layer control interface 1015 (S16). In addition, the video encoding control unit 1107 instructs the video encoding unit 1008 to perform video encoding using the video encoding rate, which 55 is the best when the video distortion D is taken into consideration, by the MCS selected according to the selection rule in the (Method 1) or (Method 2) described above. The video encoding unit 1008 performs video encoding in GOP#n using the video encoding rate designated by the video encoding 60 control unit 1107.

The cross layer rate control unit 1104 notifies the transmission channel rate control unit 1105 of the received selection MCS information as MCS control information indicating the MCS of the PD time destination which predicts the PHY transmission rate. Using the MCS control information from the cross layer rate control unit 1104, the transmission chan20

nel rate control unit 1105 selects an MCS when channel coding and modulation are performed by the channel coding/ modulation unit 1011.

By the above control operation, it is possible to set the video encoding rate and the PHY transmission rate in consideration of the video distortion D. As a result, it is possible to improve the video reception quality. In addition, although MCS information is exchanged through the cross layer control interface 1015 in the first modification, an MCS table which can be used in the channel coding/modulation unit 1011 may be shared in advance between the video encoding control unit 1107 and the cross layer rate control unit 1104. The MCS table is formed as a list in which index information of MCS is associated with the encoding rate and the modulation scheme (QPSK, 16QAM, 64QAM, and the like) corresponding to the index information, it is preferable to share this MCS table by notification from the cross layer rate control unit 1104 to the video encoding control unit 1107 through the cross layer control interface 1015 at the start of video transmission. In this manner, it is possible to reduce the amount of information which needs to be transmitted in the cross layer control interface 1015. In addition, when the above (Method 2) is used in the selection of the video encoding rate and the MCS which are the best according to the selection rule considering the video distortion D, the weight information α(MCS#k) and the Target_PER information may be written in a table so that they can be shared in advance between the video encoding control unit 1107 and the cross layer rate control unit 1104. It is preferable to share the weight information table by notification from the cross layer rate control unit 1104 to the video encoding control unit 1107 through the cross layer control interface 1015 at the start of video transmission. In this manner, it is possible to reduce the amount of information which is needed in the cross layer control interface 1015.

Second Modification of the First Example

As a second modification of the first example, a second $\alpha(MCS\#h)$ and $\alpha(MCS\#k)$ considering the packet error rate 40 example in which a method of determining the video encoding rate and the PHY transmission rate has been changed is shown. Although the configuration in which the video distortion D for the video encoding rate is calculated each time by the video distortion calculation unit 1121 is adopted in the first modification described above, it is possible to use a table showing their correspondence relationship when the video distortion for the video encoding rate is a fixed value. Accordingly it becomes unnecessary to calculate the video distortion D each time. As a result, since it is possible to reduce operations regarding the selection of the video encoding rate and the MCS, it is possible to simplify the circuit configuration or to reduce power consumption. In addition, when the video distortion for the video encoding rate is a fixed value as described above, it is possible to apply a procedure for notification of the table information regarding the video distortion D for the video encoding rate from the video encoding control unit 1107 to the cross layer rate control unit 1104 through the cross layer control interface 1015 at the start of communication or during initialization of the device.

> FIG. 16 is a flow chart showing the procedure of determining the video encoding rate and the PHY transmission rate in consideration of the video distortion related to the second modification of the first example. In the second modification, information of the video encoding rate and video distortion can be checked by the cross layer rate control unit 1104. Accordingly, MCS selection using the selection rule considering the video distortion D is performed by the cross layer

rate control unit 1104. The video encoding control unit 1107 determines whether or not it is at the start of communication for during the initialization of the device) (S21). When it is at the start of communication or during the initialization of the device, the video encoding control unit 1107 notifies the cross layer rate control unit 1104 of the video distortion table, which shows the correspondence information of the video encoding rate and the video distortion, through the cross layer control interface 1015 (522).

The cross layer rate control unit **1104** calculates the predicted PHY transmission rate PR in the same manner as in the first modification described above (S23). Then, the cross layer rate control unit **1104** searches for a plurality of MCS#k (here, k=2 or more and approximately 4 or less), which achieves a bit rate equal to the bit rate per modulation symbol obtained by the MCS#n or a bit rate in the periphery close to the bit rate per modulation symbol (including a case exceeding the bit rate per modulation symbol and a case less than the bit rate per modulation symbol), with the MCS#n used when calculating the PHY transmission rate PR. Then, the PHY transmission rates PR(MCS#n) and PR(MCS#n) when these MCS#n and MCS#k are used are calculated (S24).

Then, the cross layer rate control unit **1104** selects a video encoding rate corresponding to the last PHY transmission rate, which is comparable to or less than the calculated PHY 25 transmission rates PR(MCS#n) and PR(MCS#n), and extracts the selected video encoding rate as video encoding rate candidates. Then, using the video distortion table, the video distortion D(MCS#n) and D(MCS#k) at the time of application of each video encoding rate candidate are ³⁰ extracted (S25). Then, the cross layer rate control unit **1104** selects a video encoding rate and an MCS which are the best (which minimizes the video distortion D) according to the selection rule considering the video distortion D (S26).

Then, the cross layer rate control unit **1104** notifies the video encoding control unit **1107** of the selection video encoding rate information, which indicates the selected video encoding rate and MCS, through the cross layer control interface **1015** (S27). On the basis of the received selection video encoding rate information, the video encoding control unit 40 **1107** instructs the video encoding unit **1008** to perform video encoding using the video encoding rate at which the video distortion D is minimized by the selected MCS. The video encoding unit **1008** performs video encoding in GOP#n using the video encoding rate designated by the video encoding 45 control unit **1107**.

The cross layer rate control unit **1104** notifies the transmission channel rate control unit **1105** of the selected MCS as MCS control information indicating the MCS of the PD time destination which predicts the PHY transmission rate. Using the MCS control information from the cross layer rate control unit **1104**, the transmission channel rate control unit **1105** selects an MCS when channel coding and modulation are performed by the channel coding/modulation unit **1011**.

By the above control operation, when setting the video encoding rate and the PHY transmission rate in consideration of the video distortion D, it is not necessary to perform control through the cross layer control interface each time. Therefore, it is not necessary to take into consideration the influence of a control delay through the cross layer control interface. Moreover, in this manner, it is possible to shorten the prediction time when calculating the predicted PHY transmission rate.

Second Example

A second example corresponds to the second embodiment described above. The configuration of a wireless communication device is the same as that in the first example described above. Here, characteristic operations in the second example will be described on the basis of the configuration of the wireless transmission device shown in FIG. 9.

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The video encoding control unit 1007 determines parameters, such as the GOP size, the quantization size Q, and the video size when performing video encoding, on the basis of the information of the predicted value of the PHY transmission rate from the cross layer rate control unit 1004 acquired through the cross layer control interface 1015. Then, the video encoding control unit 1007 notifies the video encoding unit 1008 of the determined parameter and performs variable control of the video encoding rate for the video encoding unit 1008. Here, as the quantization size Q, a quantization size Q which becomes the last video encoding rate comparable to or less than the predicted value of the PHY transmission rate is selected. On the other hand, the GOP size is changed as follows.

The video encoding control unit 1007 compares the PHY transmission rate with a reference value according to changes in the predicted value of the PHY transmission rate due to propagation changes on the basis of the information regarding the predicted value of the PHY transmission rate from the cross layer rate control unit 1004, and changes the GOP size according to the difference from the reference value. In this case, as shown in FIG. 5, the GOP size is changed to the smaller size (S) when the predicted value of the PHY transmission rate is higher than the reference value, and the GOP size is changed to the larger size (L) when the predicted value of the PHY transmission rate is equal to or lower than the reference value. Here, the reference value is assumed to be a video encoding rate which becomes a PSNR saturation region boundary shown in FIG. 1. Alternatively, the reference value may be assumed to be the PHY transmission rate set at the start of video transmission.

Moreover, in addition to the above-described variable control of the GOP size, the video encoding control unit 1007 may control the video encoding unit 1008 as follows in order to adjust the video encoding resolution. When the predicted value of the PHY transmission rate is equal to or lower than the reference value, the GOP size is changed to Large, and a value which is comparable to or less than the predicted value of the PHY transmission rate and which becomes a low video encoding rate compared with a case where the PHY transmission rate is higher than the reference value is selected as the value quantization size Q. By increasing the quantization size O in this manner, the spatial resolution is reduced and accordingly the video encoding resolution is reduced. In addition, in order to reduce the video encoding resolution, it is also possible to select a parameter which reduces the frame rate (time resolution). In addition, control to increase the number of I pictures in a GOP may be further performed when reducing

By the above control operation, in addition to the effect of the first example, when the PHY transmission rate is equal to or lower than the reference value, the video encoding rate (frame rate) and the PHY transmission rate can be matched to each other by reducing the video encoding rate or the frame rate. As a result, it is possible to ensure the minimum video quality in a situation where the transmission channel conditions (propagation quality) are poor. In this manner, it is possible to suppress noticeable degradation of the video quality at the time of low transmission rate. In addition, in the case of performing further control to increase the number of I pictures in a GOP when reducing the frame rate, it is possible to reduce error propagation to related B pictures and P pictures when a reception error of I pictures occurs. As a result,

it is possible to improve the minimum video quality in a situation where the propagation quality is poor. In addition, when reducing the video encoding rate, application of error correction coding based on the lower encoding rate or the selection of an MCS using a modulation scheme with a lower modulation level are possible in the transmission channel rate control unit 1005 if the allocation resource size is fixed. Accordingly, it is possible to suppress quality degradation further

Third Example

A third example corresponds to the third and fourth embodiments described above. The configuration of a wireless communication device is the same as that in the first 15 example described above. Here, characteristic operations in the third example will be described on the basis of the configuration of the wireless transmission device shown in FIG.

In the first example, the cross layer rate control unit 1004 20 operates to predict the transmission rate (PHY transmission rate) of a wireless transmission section on the basis of the allocation resource information and the reception quality information CQI and to notify the video encoding control unit 1007 of the result through the cross layer control interface 25 1015. As a different operation from this, in the third example, not the predicted value of the PHY transmission rate but the MCS prediction value are notified to the video encoding control unit 1007 through the cross layer control interface **1015**. When the resource assigned by the resource control 30 unit 1003 (reserved allocation, preserved allocation, continuous allocation, and persistent allocation) is fixed, the PHY transmission rate is determined uniquely by the MCS selection since the resource size is fixed. In this case, therefore, the cross layer rate control unit 1004 notifies the video encoding 35 control unit 1007 of the MCS prediction value as a transmission channel parameter of a wireless transmission section.

The video encoding control unit 1007 determines parameters, such as the GOP size, the quantization size Q, and the video size when performing video encoding, on the basis of 40 the information of the MCS prediction value from the cross layer rate control unit 1004 acquired through the cross layer control interface 1015. Then, the video encoding control unit 1007 notifies the video encoding unit 1008 of the determined parameter and performs variable control of the video encod- 45 ing rate for the video encoding unit 1008. Here, for the GOP size, the MCS prediction value is compared with the reference value on the basis of the information of the MCS prediction value according to changes in the MCS prediction value due to propagation changes, and the GOP size is 50 changed according to the size relationship between the MCS prediction value and the reference value. In this case, as shown in FIG. 6, the GOP size is changed to the smaller size (S) when the MCS prediction value is larger than the reference value, and the GOP size is changed to the larger size (L) 55 when the MCS prediction value is equal to or lower than the reference value. Here, it is assumed that the reference value is obtained by dividing the video encoding rate as a PSNR saturation region boundary by the number of data symbols included in an allocation resource. Alternatively, the refer- 60 ence value may be obtained by dividing the initial MCS setting value set at the start of video transmission or the initial PHY transmission rate set at the start of video transmission by the number of data symbols included in an allocation

By the above control operation, in addition to the effect of the first example, the error rate at the time of video transmis24

sion can be further improved by changing the GOP size to Small in a high-modulation multi-level region with relatively low resistance to errors by propagation changes (16QAM, 64QAM, and the like). As a result, it is possible to improve the video reception quality.

In addition, as an operation corresponding to the fourth embodiment, the video encoding control unit 1007 may divide a set of all possible MCS values of MCS prediction values (MCS set) into a plurality of regions and change the GOP size according to the reference rate set in each region.

In this case, for example, as shown in FIG. 7, grouping is performed for each MCS using the same modulation level. In this case, the encoding rate R is different within the same group (region). In the example shown in FIG. 7, an example of grouping to three regions of 64QAM, 16QAM, and QPSK is shown. In each region, the GOP size is changed to Small when the encoding rate is higher than a reference rate, and the GOP size is changed to Large when the encoding rate is equal to or lower than the reference rate. The reason is that the GOP size is changed to Small since resistance to errors decreases as the encoding rate increases and the GOP size is changed to Large since resistance to errors increases as the encoding rate decreases. As described above, by determining the GOP size on the basis of error resistance in order to reduce the error rate of video transmission with respect to propagation changes, it is possible to improve the video reception quality. In addition, values of Large and Small of the changed GOP size may be different values for respective regions. By setting the optimal size of GOP Large/GOP Small in each region in the case of transmitting different content, such as High-definition video (high-resolution video, HD video) content and standard-resolution video (SD video) content, it is possible to improve the video quality further.

Fourth Example

A fourth example corresponds to the fifth embodiment described above. The configuration of a wireless communication device is the same as that in the first example described above. Here, characteristic operations in the fourth example will be described on the basis of the configuration of the wireless transmission device shown in FIG. 9.

The video encoding control unit 1007 determines parameters, such as the GOP size, the quantization size Q, and the video size when performing video encoding, on the basis of the information of the predicted value of the PHY transmission rate from the cross layer rate control unit 1004 acquired through the cross layer control interface 1015. Then, the video encoding control unit 1007 notifies the video encoding unit 1008 of the determined parameter and performs variable control of the video encoding rate for the video encoding unit 1008. Here, as the quantization size Q, a quantization size Q which becomes the last video encoding rate comparable to or less than the predicted value of the PHY transmission rate is selected. On the other hand, the GOP size is changed as follows.

The video encoding control unit 1007 compares the PHY transmission rate with a reference value according to changes in the predicted value of the PHY transmission rate due to propagation changes on the basis of the information regarding the predicted value of the PHY transmission rate from the cross layer rate control unit 1004, and changes the GOP size according to the difference from the reference value. In this case, the GOP size is changed to the smaller size when the predicted value of the PHY transmission rate is higher than the reference value, and the GOP size is changed to the larger size when the predicted value of the PHY transmission rate is

equal to or lower than the reference value. Here, the reference value is assumed to be a video encoding rate which becomes a PSNR saturation region boundary shown in FIG. 1. Alternatively, the reference value may be assumed to be the PHY transmission rate set at the start of video transmission.

In the fourth example, the PHY transmission rate is divided into a plurality of regions, and the GOP size is changed according to the reference rate in each region. In addition, a plurality of divided regions may have transmission rate overlap portions. In this case, for example, as shown in FIG. 8, the PHY transmission rate is divided into a high video encoding rate (HD transmission) region and a low video encoding rate (SD transmission) region, and a reference rate is set in each region. In addition, in each of the high video encoding rate region and the low video encoding rate region, the GOP size is changed on the basis of the perceived video quality in the region. In each region, the GOP size is changed to Small when the encoding rate is higher than a reference rate, and the GOP size is changed to Large when the encoding rate is equal to or lower than the reference rate. In addition, values of Large and $\,\,^{20}$ Small of the changed GOP size may be different values for respective regions.

By the above control operation, the video reception quality in each transmission rate region can be improved by selecting the GOP size on the basis of a perceived video quality reference for each of the plurality of transmission rate regions.

Fifth Example

The fifth example is an example applied to uplink video ³⁰ transmission in a state where the wireless transmission device is a terminal of the wireless communication system and the wireless receiving device is a base station of the wireless communication system. In this case, the wireless transmission device (terminal) transmits video data on the basis of a ³⁵ resource allocation instruction from the wireless receiving device (base station).

Configuration and Operation of the Wireless Transmission Device

FIG. 17 is a block diagram showing the configuration of the wireless transmission device related to the fifth example. The wireless transmission device is configured to include a signal receiving unit 1501, a reception quality information extraction unit 1502, an allocation resource information extraction unit 1503, a cross layer rate control unit 1504, a transmission channel rate control unit 1505, a PHY transmission rate request information generation unit 1506, a video encoding control unit 1507, a video encoding unit 1508, a video encoding information addition unit 1509, a packet generation unit 1510, a channel coding/modulation unit 1511, a resource mapping unit 1512, and a signal transmission unit 1513.

The signal receiving unit **1501** receives a wireless signal transmitted from a wireless communication device, which is a partner that performs video transmission through wireless communication, through an antenna and performs frequency conversion of the received signal from the carrier frequency band to the baseband frequency band. The reception quality information extraction unit **1502** extracts CQI, as reception quality information of the wireless transmission channel transmitted from the wireless communication partner, on the basis of the signals received by the signal receiving unit **1501**.

The allocation resource information extraction unit 1503 extracts allocation resource information from the control information transmitted from the wireless communication partner on the basis of the signal received by the signal received.

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ing unit **1501**. The allocation resource information includes allocation information of the resource at a time and a frequency, which is used for video transmission, among the available wireless resources (frequency carrier band) assigned by the image-transmission-side wireless communication device. In this case, as the allocation resource information, resource position information, resource size information, resource arrangement information (distributed allocation or localized allocation), and the like are included. In addition, the allocation resource information includes MCS information, which is information regarding the encoding rate R and modulation scheme information (QPSK, 16QAM, 64QAM, and the like), in the channel coding/modulation unit **1511** when performing video transmission.

The transmission channel rate control unit **1505** sets the encoding rate R and the modulation scheme information (QPSK, 16QAM, 64QAM, and the like), which are used in the channel coding/modulation unit **1511**, according to the MCS information extracted by the allocation resource information extraction unit **1503**, and outputs the MCS information to the channel coding/modulation unit **1511**.

The video encoding unit 1508 performs video encoding of the video content (video source), which has video data including a moving image or a still image as a source, on the basis of the output of the video encoding control unit 1507. As video encoding, video encoding methods, such as H.264 and MPEG, are used. In the video encoding process, timing of a minimum unit of video encoding rate control is a GOP unit.

The video encoding information addition unit **1509** adds an encoding parameter, which is used at the time of video encoding in the video encoding unit **1508**, to the GOP unit as video encoding information. Here, the video encoding information addition unit **1509** adds video encoding information to each header #n of the n-th GOP#n and outputs the result. The packet generation unit **1510** forms a packet based on a predetermined format for the output of the video encoding information addition unit **1509** and outputs the result. In addition, a CRC bit for error detection is added to each packet.

The channel coding/modulation unit 1511 performs channel coding (transmission channel encoding) and modulation for the input packet on the basis of the MCS information (including the encoding rate and the modulation scheme) designated from the transmission channel rate control unit 1505. In this case, the channel coding/modulation unit 1511 generates bit data by performing an error correction coding process with the designated encoding rate R, and also generates symbol data by performing modulation on the basis of the designated modulation scheme (QPSK, 16QAM, 64QAM, and the like).

The resource mapping unit 1512 maps the PHY transmission rate request information on the resource determined in advance, and assigns the output of the channel coding/modulation unit 1511 to the wireless resource on the time and frequency on the basis of the allocation resource information extracted by the allocation resource information extraction unit 1503. Here, when OFDMA is used as secondary modulation, the resource size is set with a resource unit, which includes a predetermined number of subcarriers and a predetermined number of OFDM symbols, as a minimum allocation unit. The signal transmission unit 1513 performs frequency conversion of the output of the resource mapping unit 1512 from the baseband frequency band to the carrier frequency band and outputs the result to the wireless transmission channel through an antenna so that the result is transmitto the wireless communication device of communication partner.

The cross layer rate control unit 1504 predicts the transmission rate (PHY transmission rate) of a wireless transmission section on the basis of the allocation resource information and the reception quality information CQI, and notifies the video encoding control unit 1507 of the result through the cross layer control interface 1515. Here, the PHY transmission rate prediction process is performed in the same manner as in the first example shown in FIGS. 11 and 12. That is, in consideration of the processing time PD until the n-th video encoding unit GOP#n encoded and output by the video encoding unit 1508 is transmitted through the wireless transmission channel, the CQI estimate of the PD time destination is calculated from the reception quality situation of a current and a previous time of the reception quality information CQI acquired from the reception quality information extraction unit 1502. Then, an MCS (MCS#n) by which the target packet error rate (PER) is acquired is selected, and the transmission rate in a wireless transmission section is calculated using the allocation resource information. The calculated transmission 20 rate information or the selected MCS information is output to

In this manner, the video encoding control unit **1507** can acquire the predicted value of the PHY transmission rate for ²⁵ the GOP#n at the timing before video encoding of the target GOP#n starts. On the basis of the predicted value of the PHY transmission rate, the video encoding control unit **1507** can set parameters of video encoding, such as a GOP size change, a quantization size change, and a frame rate change, according to band changes in the wireless transmission channel (transmission rate change and propagation change).

the PHY transmission rate request information generation

unit 1506 together with the information of predicted time.

The video encoding control unit **1507** determines parameters, such as the GOP size, the quantization size Q, and the video size when performing video encoding, on the basis of the information of the predicted value of the PHY transmission rate from the cross layer rate control unit **1504** acquired through the cross layer control interface **1515**. Then, the video encoding control unit **1507** notifies the video encoding unit **1508** of the determined parameter and performs variable control of the video encoding rate for the video encoding unit **1508**. The operation of the video encoding control unit **1507** is the same as that in each of the first to fourth examples described above, and variable control of the GOP size described in each of the first to fourth examples may be 45 applied. Here, explanation thereof will be omitted.

The PHY transmission rate request information generation unit **1506** generates information including the information of predicted time and the calculated transmission rate information or the selected MCS information, which is output from 50 the cross layer rate control unit **1504**, as PHY transmission rate request information based on a predetermined format.

Configuration and Operation of the Wireless Receiving Device

FIG. 18 is a block diagram showing the configuration of the wireless receiving device related to the fifth example. The wireless receiving device is configured to include a signal receiving unit 2501, a reception quality estimation unit 2502, 60 a reception quality information generation unit 2503, a PHY transmission rate request information extraction unit 2504, a data extraction unit 2505, a demodulation/error correction decoding unit 2506, a packet error detection unit 2507, a video decoding unit 2508, a video data error detection/compensation unit 2509, an error situation notification information generation unit 2510, a signal transmission unit 2511, an

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allocation resource control unit 2512, and an allocation resource information generation unit 2513.

The signal receiving unit 2501 receives a wireless signal transmitted from the wireless communication device, which is a partner that performs video transmission through wireless communication, through an antenna and performs frequency conversion of the received signal from the carrier frequency band to the baseband frequency band. On the basis of the signal received by the signal receiving unit 2501, the reception quality estimation unit 2502 estimates the reception quality of the wireless transmission channel between the partner device and the host device, for example, using a reception result of a reference signal. The reception quality information generation unit 2503 generates CQI as the reception quality information on the basis of the output of the reception quality estimation unit 2502.

When the signal received by the signal receiving unit 2501 has been subjected to secondary modulation, such as OFDMA, the PHY transmission rate request information extraction unit 2504 performs the demodulation operation to extract the modulated symbolic data in which notification information is included, thereby extracting the PHY transmission rate request information. Here, the PHY transmission rate request information includes transmission rate information or MCS information determined on the transmission side and information of predicted time.

On the basis of the extracted PHY transmission rate request information, the allocation resource control unit 2512 determines the allocation of the resource at a time and a frequency, which is used for video transmission, among the available wireless resources (frequency carrier band). On the basis of the resource allocation information determined by the allocation resource control unit 2512, the allocation resource information generation unit 2513 generates information including allocation resource information, which includes resource position information, resource size information, resource arrangement information, and MCS information, and various kinds of information as control information based on a predetermined format.

When the signal received by the signal receiving unit 2501 has been subjected to secondary modulation, such as OFDMA, the data extraction unit 2505 performs the demodulation operation to extract the modulated symbolic data destined for the host device. The demodulation/error correction decoding unit 2506 converts the extracted symbolic data into channel-coded (transmission-channel-coded) bit data by performing demodulation processing based on the designated modulation scheme (QPSK, 16QAM, 64QAM, and the like) on the extracted symbolic data. In addition, the demodulation/error correction decoding unit 2506 performs an error correction decoding process on the channel-coded bit data.

The packet error detection unit 2507 detects whether or not the packet has been received successfully on the basis of the CRC bit for error detection added to each packet. Then, according to the error detection result, unique index information given to each packet and ACK (reception OK) are output as packet error information to the error situation notification information generation unit 2510 when the packet has been received correctly, and unique index information given to each packet and NACK (reception NG) are output as packet error information to the error situation notification information generation unit 2010 when the packet has not been received correctly.

The video decoding unit 2508 stores primarily the packet received successfully in a buffer, and starts a video decoding process when the data which makes up the smallest unit of video encoding is prepared. Here, when the video content is

transmitted in real time, if the data which makes up the minimum unit of video encoding is not prepared in real time, processing for discarding the packet data acquired until then is performed. In the video decoding process, the video decoding unit 2508 decodes the video data according to the encoding parameter set on the transmission side on the basis of the video encoding information included in the packet, thereby reproducing the received video content.

The video data error detection/compensation unit **2509** detects a loss (video data error) of the video data based on a packet which has not been acquired in real time. In addition, when the loss of video data is detected, compensation for the video data is performed. As compensation for video data, for example, video data on the same screen from previously is used again on the basis of the position on the screen (on the 15 field) formed by the video data. As a result, degradation of the video quality can be suppressed. In addition, when the loss of video data is detected at a predetermined frequency or higher, the information is output to the error situation notification information generation unit **2510** as video data loss information.

The error situation notification information generation unit 2510 generates error situation notification information, in a format in which each error can be distinguished, from the packet error information in the packet error detection unit 2507 or the video data loss information in the video data error detection/compensation unit 2509. The signal transmission unit 2511 performs frequency conversion of the allocation resource information, the error situation notification information, and the reception quality information CQI from the 30 baseband frequency band to the carrier frequency band and outputs the result to the wireless transmission channel through an antenna so that the result is transmitted to the wireless communication device of the communication partner.

By the above configuration and operation, also in the uplink from the terminal of the wireless communication system to the base station, similar to the downlink from the base station of the wireless communication system to the terminal shown in the first to fourth examples, the parameter update 40 interval in the video encoding control unit 1507 can be changed on the basis of the video encoding timing of the GOP unit in the video encoding unit 1508, and the PHY transmission rate (transmission band width) and the GOP size can be controlled so as to be associated with each other. That is, the 45 GOP size can be changed according to the size of the PHY transmission rate (propagation change). In this manner, it is possible to improve the video reception quality under propagation changes.

In addition, various changes and applications of the present 50 invention may be made by those skilled in the art on the basis of the description of this specification and known techniques without departing from the spirit and scope of the present invention, and these are also included in the range of the request for protection. In addition, the respective components 55 in the embodiments described above may be arbitrarily combined without departing from the scope of the invention.

Moreover, although the case of the configuration where the present invention is realized by hardware has been described as an example in the above embodiments, the present invention may also be realized by software.

Each functional block used to describe the embodiment and each modification is typically implemented by an LSI, which is an integrated circuit. Each functional block may be integrated into one chip, or a portion of or the entire functional block may be integrated into one chip. Here, the LSI is used as the integrated circuit, but the integrated circuit may be

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called an IC, a system LSI, a super LSI, or an ultra LSI according to the degree of integration.

In addition, a circuit integration method is not limited to LSI, but circuit integration may be implemented by a dedicated circuit or a general-purpose processor. After the LSI circuit is manufactured, a programmable FPGA (Field Programmable Gate Array) or a reconfigurable processor capable of reconfiguring the connection of circuit cells in the LSI circuit or the setting thereof may be used.

When a circuit integration technique capable of replacing LSI appears with the progress of semiconductor technology or other technologies derived from the semiconductor technology, the technique may be used to integrate the functional blocks. For example, biotechnology can be applied.

This application is based on Japanese Patent Application (Japanese Patent Application No. 2010-086225) filed on Apr. 2, 2010, the disclosure of which is incorporated herein by reference in its entirety.

INDUSTRIAL APPLICABILITY

The present invention has the effect that it is possible to improve the video quality on the receiving side further when controlling the transmission channel parameters and the video encoding parameters so as to be linked to each other in video transmission. For example, the present invention may be applied to a communication device and the like which perform cross layer optimization, and is useful as a wireless communication device, a wireless communication method, and the like which perform video transmission using wireless transmission.

REFERENCE SIGNS LIST

301: video encoding unit

302: channel coding/modulation unit

303: signal transmission unit

304: cross layer rate control unit

1001: signal receiving unit

1002: reception quality information extraction unit

1003: resource control unit

1004, 1104: cross layer rate control unit

1005, 1105: transmission channel rate control unit

1006: control information generation unit

1007, 1107: video encoding control unit

1008: video encoding unit

1009: video encoding information addition unit

1010: packet generation unit

1011: channel coding/modulation unit1012: resource mapping unit

1013: signal transmission unit

1015. Signai transmission unit

1015: cross layer control interface

1021: CQI information storage section

1022: predicted PHY transmission rate calculation section

1121: video distortion calculation unit

1501: signal receiving unit

1502: reception quality information extraction unit

1503: allocation resource information extraction unit

1504: cross layer rate control unit

1505: transmission channel rate control unit

1506: PHY transmission rate request information generation unit

1507: video encoding control unit

1508: video encoding unit

1509: video encoding information addition unit

1510: packet generation unit

1511: channel coding/modulation unit

1512: resource mapping unit

1513: signal transmission unit

1515: cross layer control interface

2001: signal receiving unit

2002: reception quality estimation unit

2003: reception quality information generation unit

2004: control information extraction unit

2005: data extraction unit

2006: demodulation/error correction decoding unit

2007: packet error detection unit

2008: video decoding unit

2009: video data error detection/compensation unit

2010: error situation notification information generation unit

2011: signal transmission unit

2501: signal receiving unit

2502: reception quality estimation unit

2503: reception quality information generation unit

2504: PHY transmission rate request information extraction unit

2505: data extraction unit

2506: demodulation/error correction decoding unit

2507: packet error detection unit

2508: video decoding unit

2509: video data error detection/compensation unit

2510: error situation notification information generation unit

2511: signal transmission unit

2512: allocation resource control unit

2513: allocation resource information generation unit The invention claimed is:

1. A wireless communication device comprising:

a video encoding unit configured to perform video encoding on video data to generate an encoded video data;

a channel coding and modulation unit configured to perform error correction coding and modulation on the encoded video data to generate channel coded video data;

a signal transmission unit configured to transmit the channel coded video data; and

a control unit configured to perform variable control of a GOP (Group of Pictures) size in the video encoding on the basis of a size of a transmission channel parameter corresponding to a predicted value of a transmission rate on a transmission channel through which the channel 45 coded video data is transmitted.

wherein the GOP size is controlled so as to become smaller than a determined size when the transmission channel parameter is larger than a determined reference value.

2. The wireless communication device according to claim 50

wherein the GOP size is controlled so as to become larger than the determined size when the transmission channel parameter is equal to or less than the determined reference value. 32

3. The wireless communication device according to claim

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wherein, when the GOP size is controlled so as to become larger than the determined size, the control unit reduces a video encoding rate or a frame rate in the video encoding.

4. The wireless communication device according to claim

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wherein, when changing the GOP size, the control unit changes the GOP size according to a changing rate of the GOP size.

5. The wireless communication device according to claim

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wherein the transmission channel parameter is at least one of a PHY transmission rate in a physical layer and an MCS (Modulation and Coding Scheme) indicating an encoding rate and a modulation method in the error correction coding and modulation.

6. The wireless communication device according to claim

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wherein the control unit divides the PHY transmission rate or the MCS into a plurality of regions and performs variable control of the GOP size according to a reference value which is set for each of the plurality of regions.

7. The wireless communication device according to claim

1, wherein the determined reference value is a reference value of a transmission channel parameter determined on the basis of a value indicating a boundary between a saturation region, which is a region where a change in an evaluation value of perceived video quality is small and the region where a change in the evaluation value of the perceived video quality is large, with respect to a change in video distortion changing in association with a change in a video encoding rate.

8. A wireless communication method of a wireless communication device which performs transmission of video data, the method comprising:

performing video encoding on the video data to generate an encoded video data;

performing error correction coding and modulation on the encoded video data to generate channel coded video data:

transmitting the channel coded video data; and

performing variable control of a GOP (Group of Pictures) size in the video encoding on the basis of a size of a transmission channel parameter corresponding to a predicted value of a transmission rate on a transmission channel through which the channel coded video data is transmitted,

wherein the GOP size is controlled so as to become smaller than a determined size when the transmission channel parameter is larger than a determined reference value.

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